EXHIBIT F

UTC Project Information	
Project Title	DRONETIM: Dynamic Routing of Unmanned-aerial and Emergency Team Incident Management
University	North Carolina A&T State University (NCAT) Virginia Tech (VT)
Principal Investigator	Hyoshin Park
PI Contact Information	hpark1@ncat.edu, 336-285-2763
Funding Source(s) and Amounts Provided (by each agency or organization)	Federal Funds (USDOT UTC Program): $99,791 Cost-Share Funds (NCAT): $49,892
Total Project Cost	$149,683
Agency ID or Contract Number	69A3551747125
Start and End Dates	Feb 1st 2019 – July 31th 2020
Brief Description of Research Project	The project objective is to develop a cooperative vehicle system consisting of unmanned aerial vehicles and emergency response vehicles particularly busy serving for previous emergencies.
Describe Implementation of Research Outcomes (or why Not implemented) Place Any Photos Here	 The project will provide the framework to apply our model to emergency scenarios when some traffic sensors are not working properly and require more UAVs assistance.
Impacts/Benefits of Implementation (actual, not anticipated)	Pending project completion
Web Links • Reports • Project Website	Progress will be updated on website https://johnpark.club/2019/05/02/dronetim